

MIDTERM 2 FORMULAS

Second derivative test: for a function $f(x, y)$ with continuous second derivatives and critical point (a, b) , examine the quantity (sometimes called the “Hessian”)

$$d = \begin{vmatrix} f_{xx}(a, b) & f_{xy}(a, b) \\ f_{yx}(a, b) & f_{yy}(a, b) \end{vmatrix} = f_{xx}(a, b)f_{yy}(a, b) - (f_{xy}(a, b))^2$$

Cylindrical coordinates: $x = r \cos(\theta)$, $y = r \sin(\theta)$, $z = z$.

Spherical coordinates: $x = \rho \sin(\phi) \cos(\theta)$, $y = \rho \sin(\phi) \sin(\theta)$, $z = \rho \cos(\phi)$.

Integration in polar coordinates example:

$$\iint_R f(x, y) dA = \int_a^b \int_{f_1(\theta)}^{f_2(\theta)} f(r \cos(\theta), r \sin(\theta)) r dr d\theta.$$

Mass m of a lamina R with density $\rho(x, y)$: $m = \iint_R \rho(x, y) dA$

Moments of mass with respect to x - and y -axis: $M_x = \iint_R y \rho(x, y) dA$, $M_y = \iint_R x \rho(x, y) dA$

Center of mass: $(\bar{x}, \bar{y}) = (M_y/m, M_x/m)$

Moment of inertia about the x - and y -axis: $I_x = \iint_R y^2 \rho(x, y) dA$, $I_y = \iint_R x^2 \rho(x, y) dA$

Radius of gyration for object with mass m and moment of inertia I : $\bar{r} = \sqrt{I/m}$

Surface area for surface $z = f(x, y)$ over the domain R : $\iint_R \sqrt{1 + f_x(x, y)^2 + f_y(x, y)^2} dA$

Integration in cylindrical coordinates example:

$$\iiint_R f(x, y, z) dV = \int_a^b \int_{f_1(\theta)}^{f_2(\theta)} \int_{g_1(r, \theta)}^{g_2(r, \theta)} f(r \cos(\theta), r \sin(\theta), z) r dz dr d\theta.$$

Integration in spherical coordinates example:

$$\iiint_R f(x, y, z) dV = \int_a^b \int_{f_1(\theta)}^{f_2(\theta)} \int_{g_1(\phi, \theta)}^{g_2(\phi, \theta)} f(\rho \sin(\phi) \cos(\theta), \rho \sin(\phi) \sin(\theta), \rho \cos(\phi)) \rho^2 \sin(\phi) d\rho d\phi d\theta.$$

Jacobian for the change of variables transformation $x = g(u, v)$, $y = h(u, v)$: $\left| \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \right|$

Line integral of vector field $\mathbf{F}(x, y, z) = \langle M, N, P \rangle$ on oriented curve C , parametrized by $\mathbf{r}(t)$, $a \leq t \leq b$:

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C M dx + N dy + P dz = \int_C \mathbf{F} \cdot \mathbf{T} ds = \int_a^b \mathbf{F}(x(t), y(t), z(t)) \cdot \mathbf{r}'(t) dt$$

For the vector field $\mathbf{F} = \langle M, N, P \rangle$, $\text{curl } \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix}$ and $\text{div } \mathbf{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$