

## MAT 203 LECTURE OUTLINE 9/27

- Given a function  $z = f(x, y)$  and a point  $(x_0, y_0)$ , we can find the tangent plane to the graph of  $f(x, y)$  at the point  $(x_0, y_0, f(x_0, y_0))$ . This is essentially the same thing as asking for the linearization of  $f(x, y)$  at  $(x_0, y_0)$ . Recall that the solution to this is

$$z = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) + f(x_0, y_0).$$

- We want to consider the same problem but for other surfaces. A surface does not need to be the graph of a function; a simple example is the sphere, given by the equation  $x^2 + y^2 + z^2 = 1$ . One way to think of a surface is as the level set of a function of three variables: the set of points satisfying  $F(x, y, z) = 0$  for some differentiable function  $F(x, y, z)$ .
- The same ideas we discussed about the gradient for two-variable functions apply here. Namely, the gradient is a vector that is orthogonal to the level set  $F(x, y, z) = 0$  at each point and that points in the direction of maximum increase for  $F(x, y, z)$ . The equation of the tangent plane at  $(x_0, y_0, z_0)$  is then

$$F_x(x, y, z)(x - x_0) + F_y(x, y, z)(y - y_0) + F_z(x, y, z)(z - z_0) = 0.$$

Observe how this is consistent with the equation in the first bullet point.

- Example.** Consider the hyperboloid  $z^2 - 2x^2 - 2y^2 = 12$ . Find the tangent plane at  $(1, -1, 4)$ .  
This is given by  $x - y - 2z + 6 = 0$ .
- We begin section 13.8 on Extrema. We recall some definitions. Consider a function  $f(x, y)$  defined on a planar region  $D$ .
  - The region  $D$  is *closed* if it contains all its boundary points.
  - The region  $D$  is *bounded* if it contained inside a ball of radius  $r$  for some  $r > 0$ .
  - The *maximum* (or *absolute maximum*) of  $f(x, y)$  (if it exists) is the value  $M$  such that (i)  $f(a, b) = M$  for some  $(a, b)$  in  $D$ , and (ii)  $f(x, y) \leq M$  for all  $(x, y)$  in  $D$ .
  - The *minimum* (or *absolute minimum*) of  $f(x, y)$  (if it exists) is the value  $m$  such that (i)  $f(a, b) = m$  for some  $(a, b)$  in  $D$ , and (ii)  $m \leq f(x, y)$  for all  $(x, y)$  in  $D$ .
- We also define *relative/local maxima* and *relative/local minima* to be values such that the same property holds if we replace  $D$  by **some disk** around the point  $(a, b)$ .
- The Extreme Value Theorem states that **if**  $D$  is closed and bounded, **then** any continuous function  $f$  defined on  $D$  has a maximum and a minimum. That is, there is a point  $(a, b)$  in  $D$  such that  $f(x, y) \leq f(a, b)$  for all points  $(x, y)$  in  $D$ , and a point  $(c, d)$  in  $D$  such that  $f(c, d) \leq f(x, y)$  for all points  $(x, y)$  in  $D$ . If  $D$  is not closed or not bounded, then such a function  $f$  may or may not have a maximum or minimum. Also, note that a maximum or minimum may be attained by multiple points in  $D$ .

Convince yourself intuitively that the Extreme Value Theorem is true, and that its conclusion may fail if  $D$  is not closed or not bounded.

- A *critical point* of  $f$  is a point  $(x, y)$  in the interior of a domain  $D$  where  $f_x(x, y) = 0$  and  $f_y(x, y) = 0$ , or one of these partial derivatives does not exist. Here is the main principle of this section:

Any relative minimum or maximum must occur at a boundary point or a critical point.

- One method to classify critical points is the “second partials test”. Here is the statement:  
Suppose that  $f(x, y)$  is a function with continuous second partial derivatives satisfying  $f_x(a, b) = 0$  and  $f_y(a, b) = 0$ . Let

$$d = \begin{vmatrix} f_{xx}(a, b) & f_{xy}(a, b) \\ f_{yx}(a, b) & f_{yy}(a, b) \end{vmatrix} = f_{xx}(a, b)f_{yy}(a, b) - (f_{xy}(a, b))^2.$$

- (1) If  $d > 0$  and  $f_{xx}(a, b) > 0$ , then  $f$  has a relative maximum at  $(a, b)$ .
- (2) If  $d > 0$  and  $f_{xx}(a, b) < 0$ , then  $f$  has a relative minimum at  $(a, b)$ .
- (3) If  $d < 0$ , then  $f$  has a saddle point at  $(a, b)$ .
- (4) If  $d = 0$ , the test is inconclusive.